

Status of Accumulator Ring Simulation

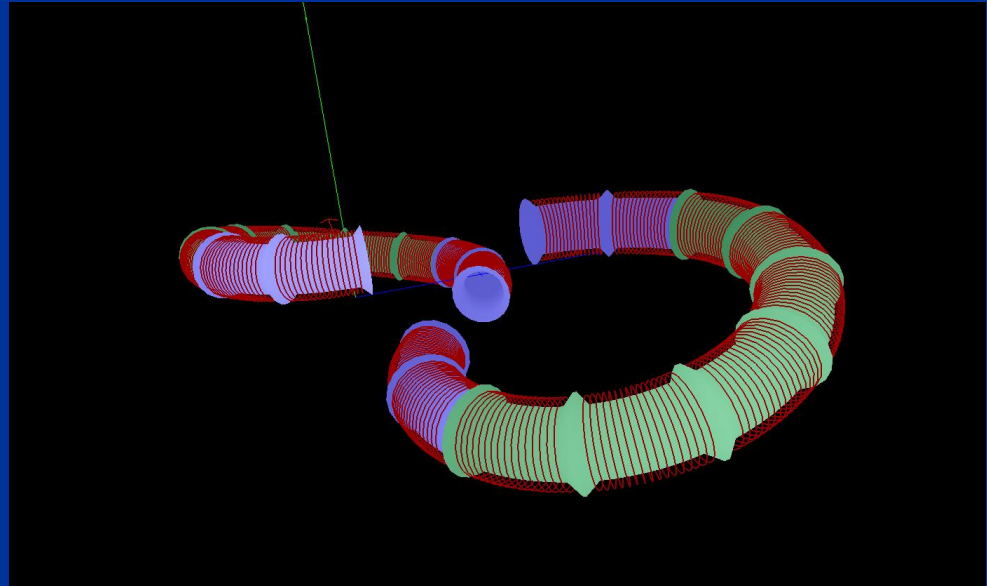
Martin Droba
Riezlern 2005

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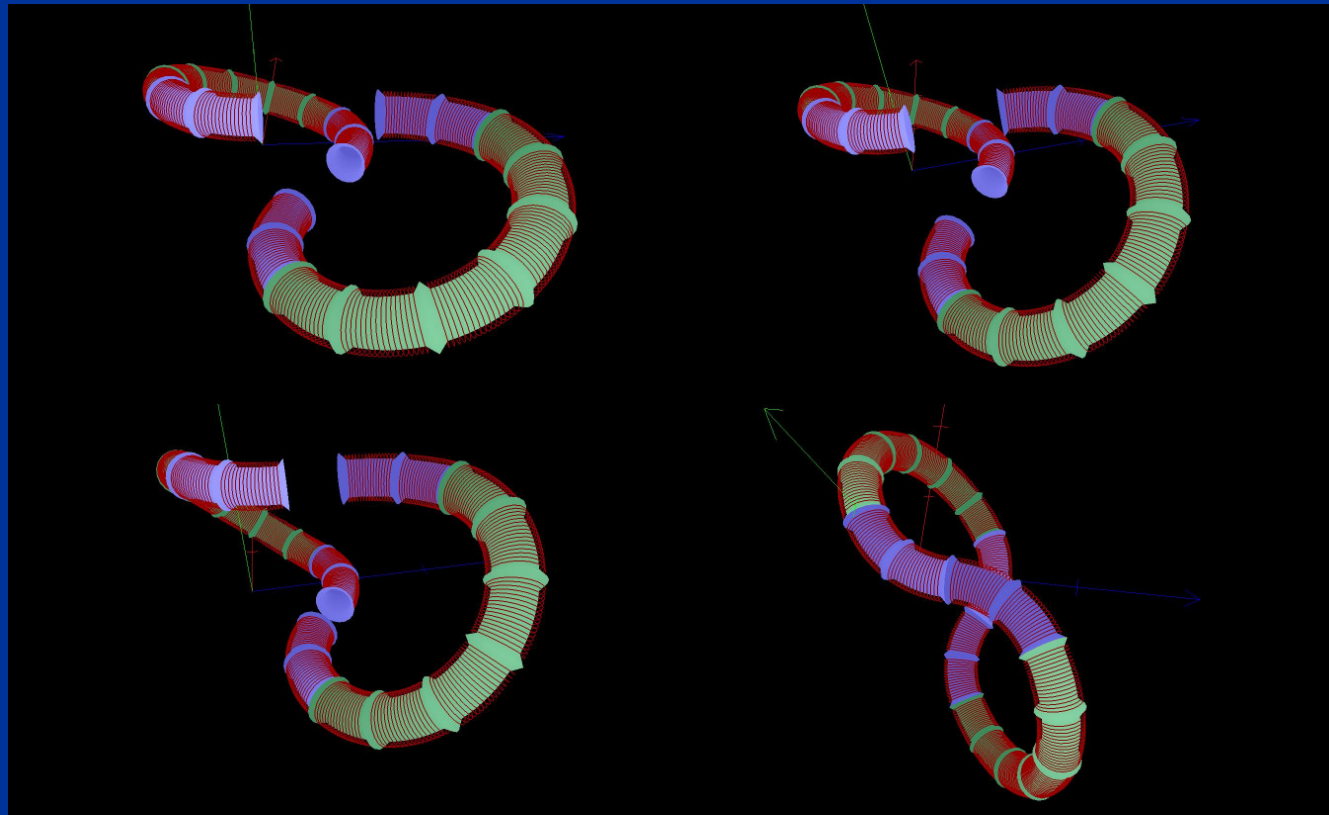
Motivation

- Accumulator ring with magnetic surfaces
- Example : 8-figure ring
 - 30° sectors, $R=0.5\text{m}$, $R_1=0.08\text{m}$
- Different designs
- Calculation of coordinate system for long term simulations
- PIC simulations



Motivation

- Different slope angles
20°, 30°, 45°, 60°
- Straight sector
0.51m, 0.42m,
0.24m, 0m



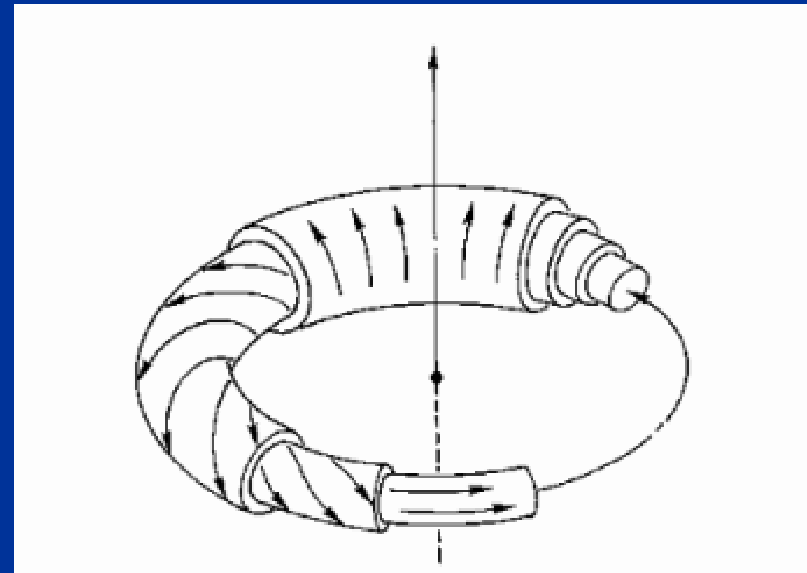
CSC(Center for Scientific Computing)

<http://www.csc.uni-frankfurt.de>

- Xeon Cluster 32bit
 - February 2003
 - 70 node Linux Cluster with 2.4 GHz dual Pentium Xeon CPUs for each node.
 - 32 nodes Myrinet, 38 nodes 100Mbit Ethernet
 - 2GB RAM
- Opteron Cluster 64bit
 - May 2004
 - 282 nodes = 564 1.8 Ghz Opteron 244 processors.
 - 64 nodes Myrinet, 218 nodes Gbit Ethernet.
 - Myrinet - 320 GFlop/s,
 - Ethernet - 650 GFlop/s.
 - 4GB RAM

Magnetic surface

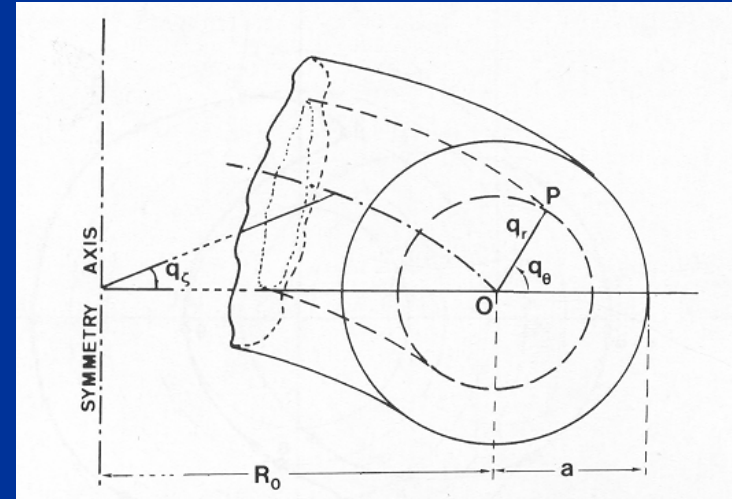
- Definition: *If a magnetic field line stays within a surface, coming arbitrarily close to any point of surface, then that surface is a magnetic surface*
- Concepts: Rotational transform(field line twist) and shear
- Example: Tokamaks, Stellarators



Magnetic surfaces

- *Why calculate magnetic surfaces?*
- Example: B=1T Electrons

$$\omega_g = qB / m = 1.76 \cdot 10^{11} \text{ Hz}$$

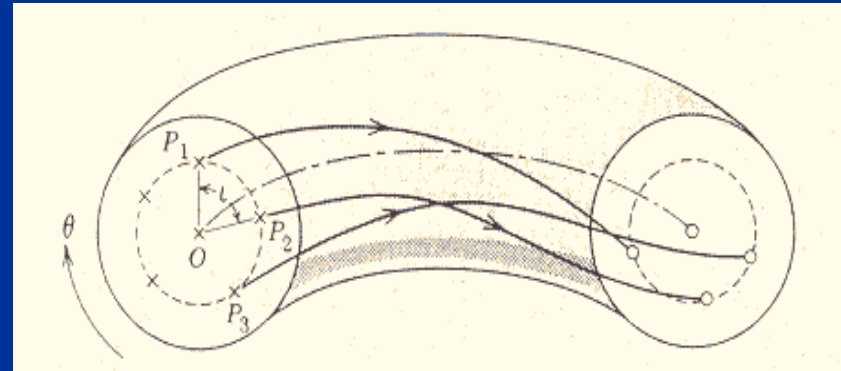


- at least 20 points per turn => time step $dt = 2.8 \cdot 10^{-13} \text{ s}$
- Averaging through the Larmor oscillation => local curvature of the field is needed in every calculation point

Magnetic surface – Computation method

- Field line tracing method
– „Follow the B-vector“
from Biot-Savart formula
- Point filtering
- NURBS (Non-Uniform Rational B-Splines) - Surfaces

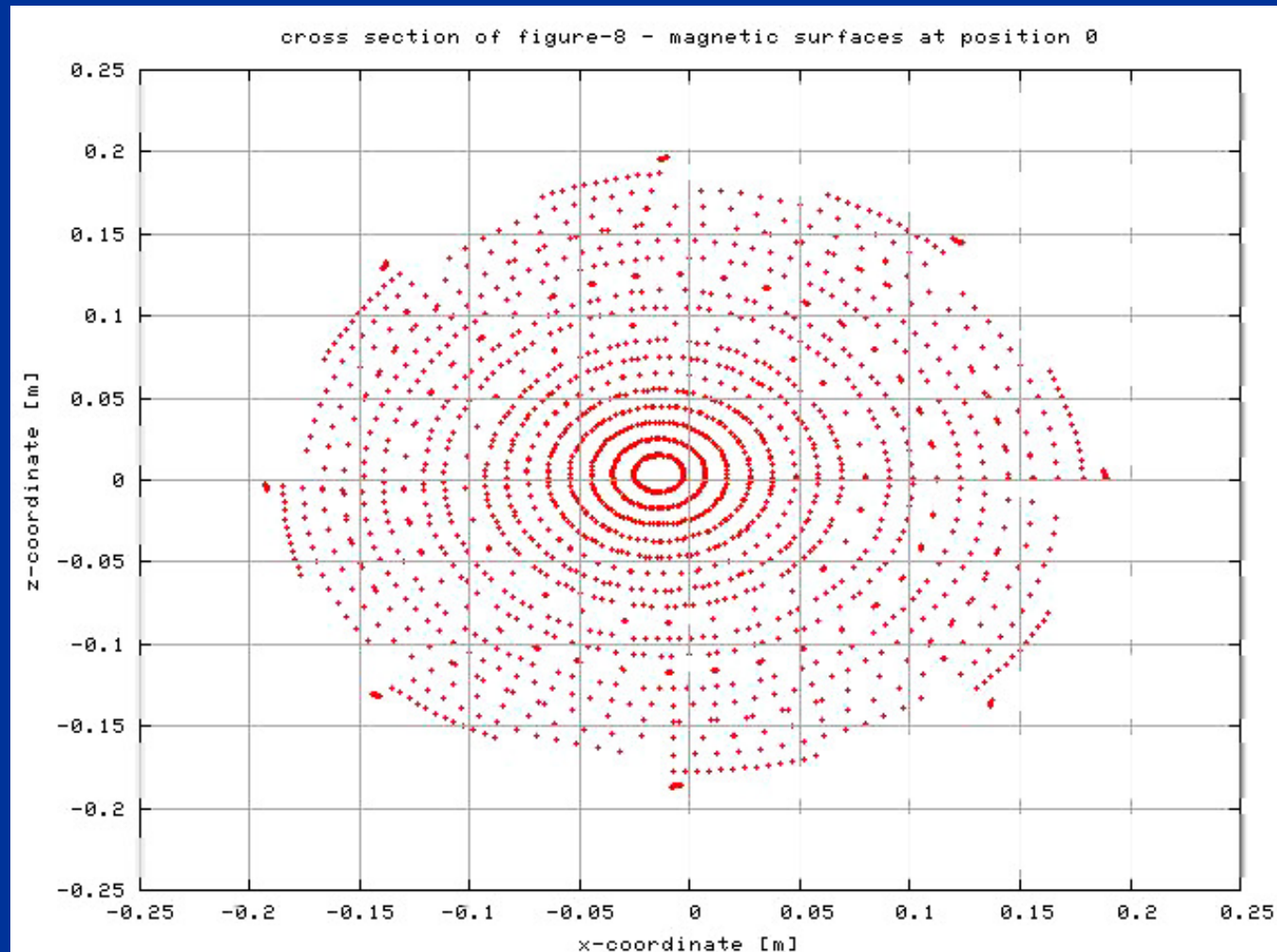
$$\vec{B} = \int \frac{\mu I}{4\pi} \frac{d\vec{l} \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$$



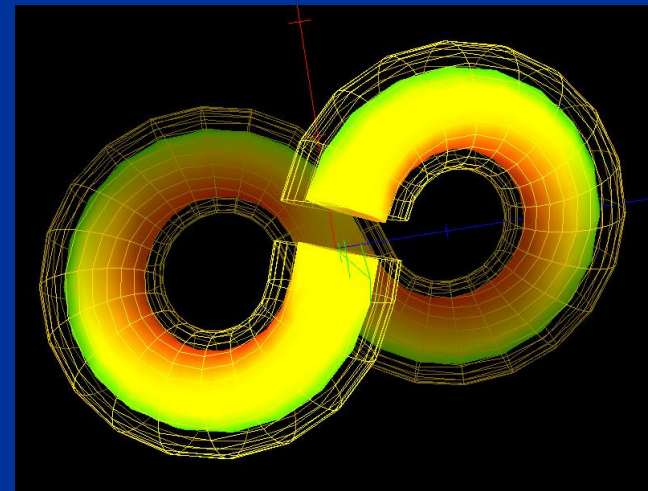
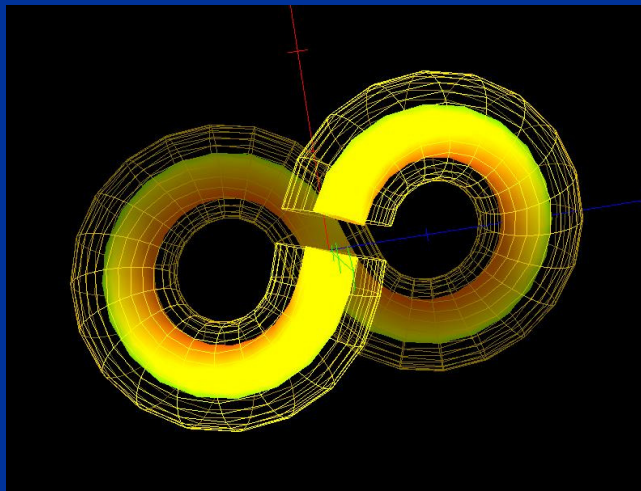
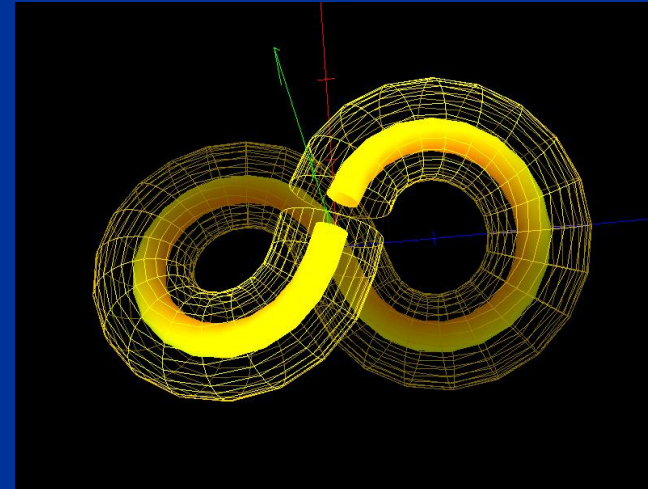
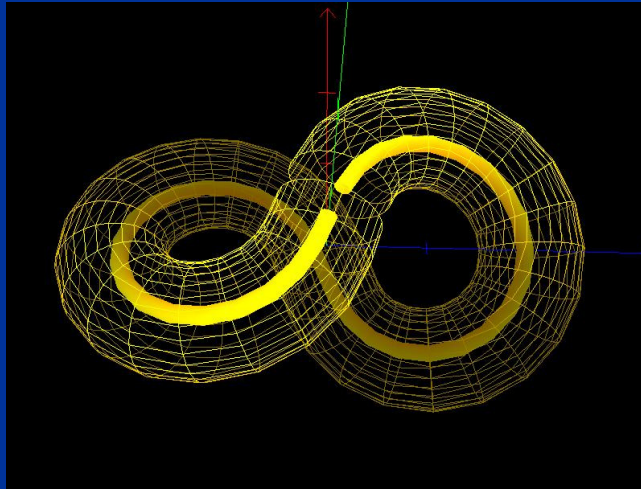
Magnetic surfaces as a 1st test object

- 10000 steps around figure-8 (1step ~ 0.8mm)
- 20 surfaces at once
= 20 processors
(independent calculations)
- 100 Turns around the figure-8
- Simulation time 50h on 20 Processors
- Computed Parameter: B, A, χ , ψ - magnetic Flux, metric tensors

Magnetic surfaces as a 1st test object



Magnetic surfaces – B field

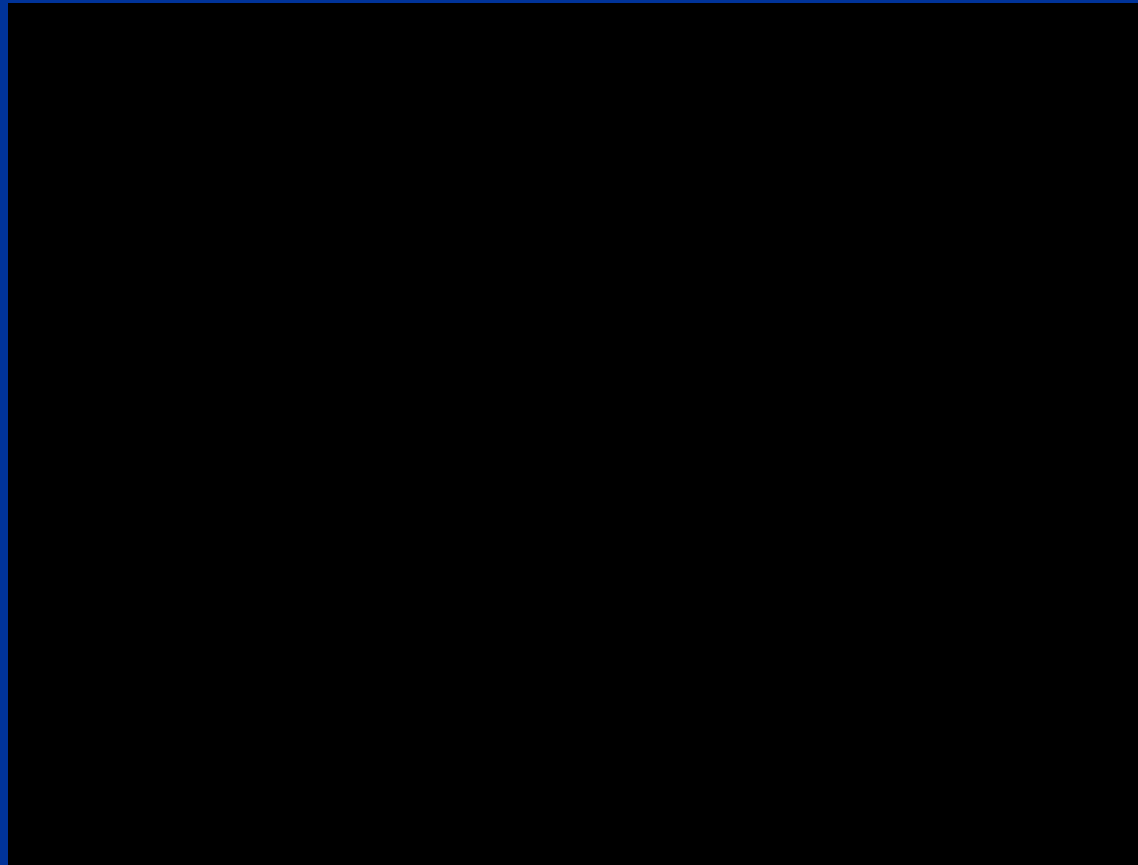


Magnetic surface

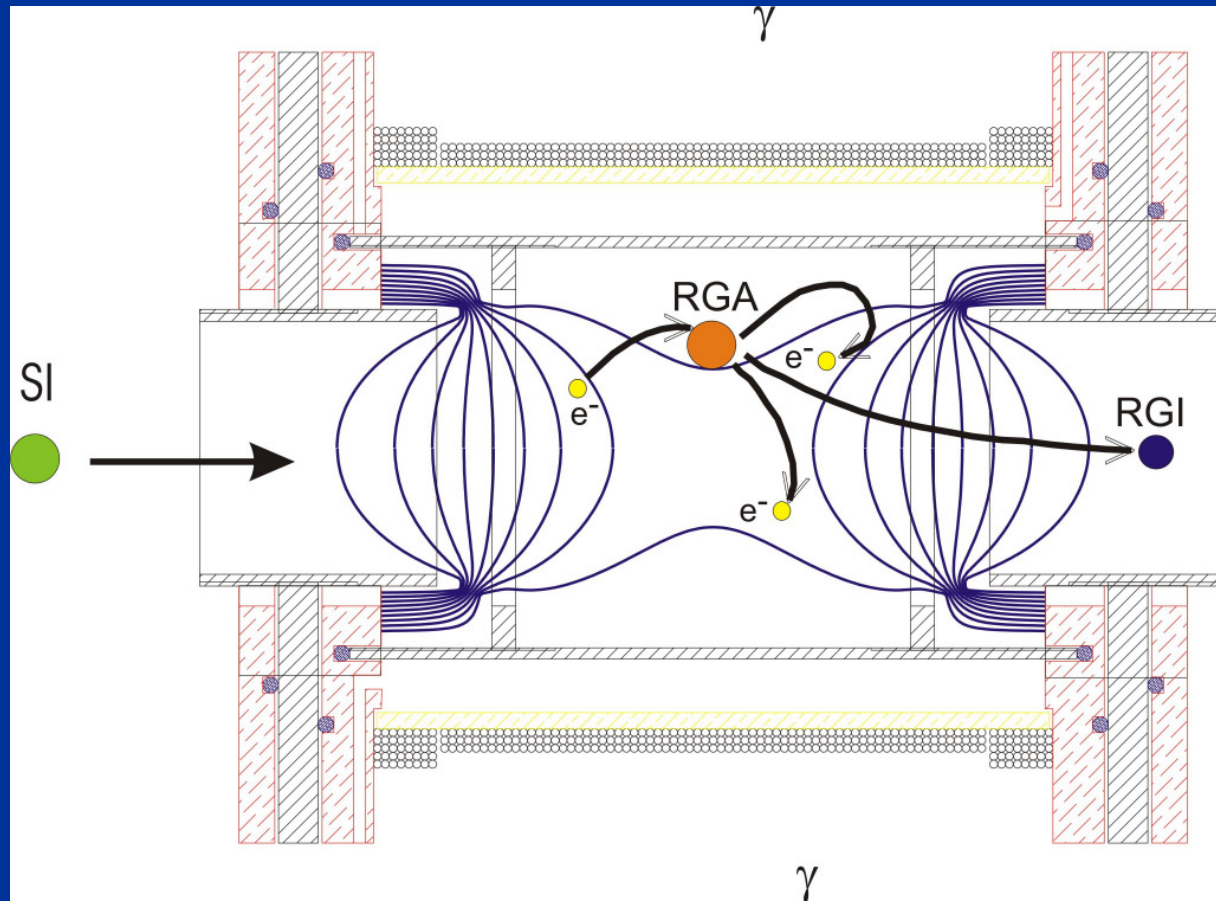
Colour coding

– B-field :
green 0.6T –
red 1.4T

*Important for
reflection of
particles*



Gabor lens as a 2nd test object

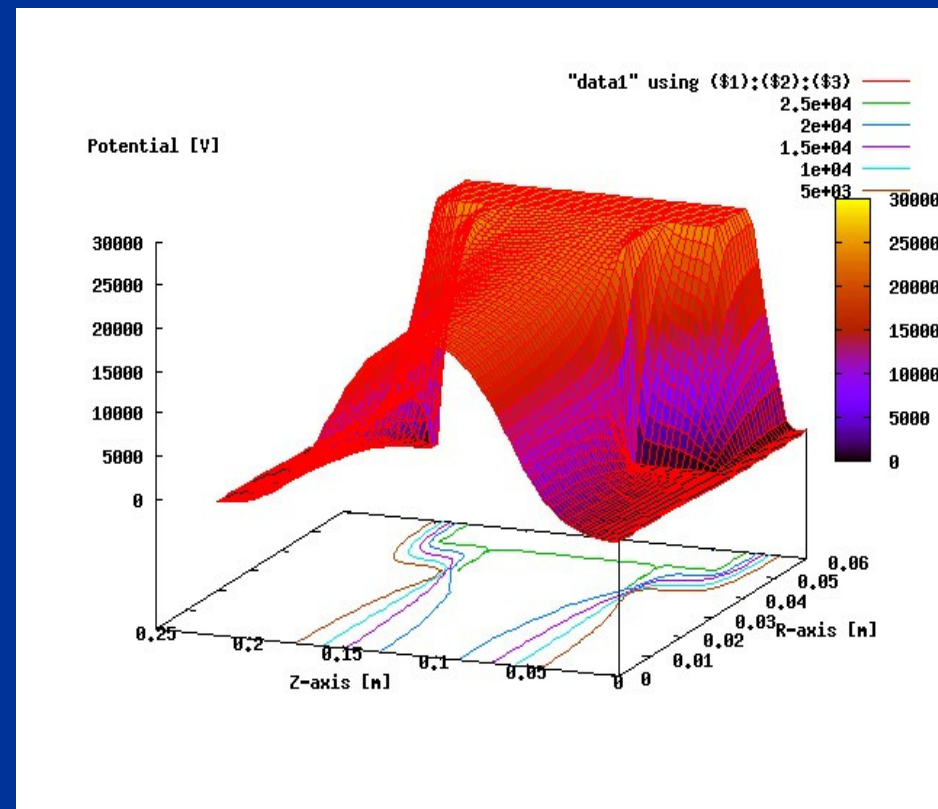


Gabor lens - Field

- Sparse matrix format – saving of memory
- Iteration methods – BiCGSTAB (Bi-Conjugate Gradient Stabilized)
- Cutting in longitudinal direction => depending on number of processors
- Changing of boundary data in every step
- 3D-Poisson Equation in cylindrical mesh
- $r=0$ Problems => Gauss formula

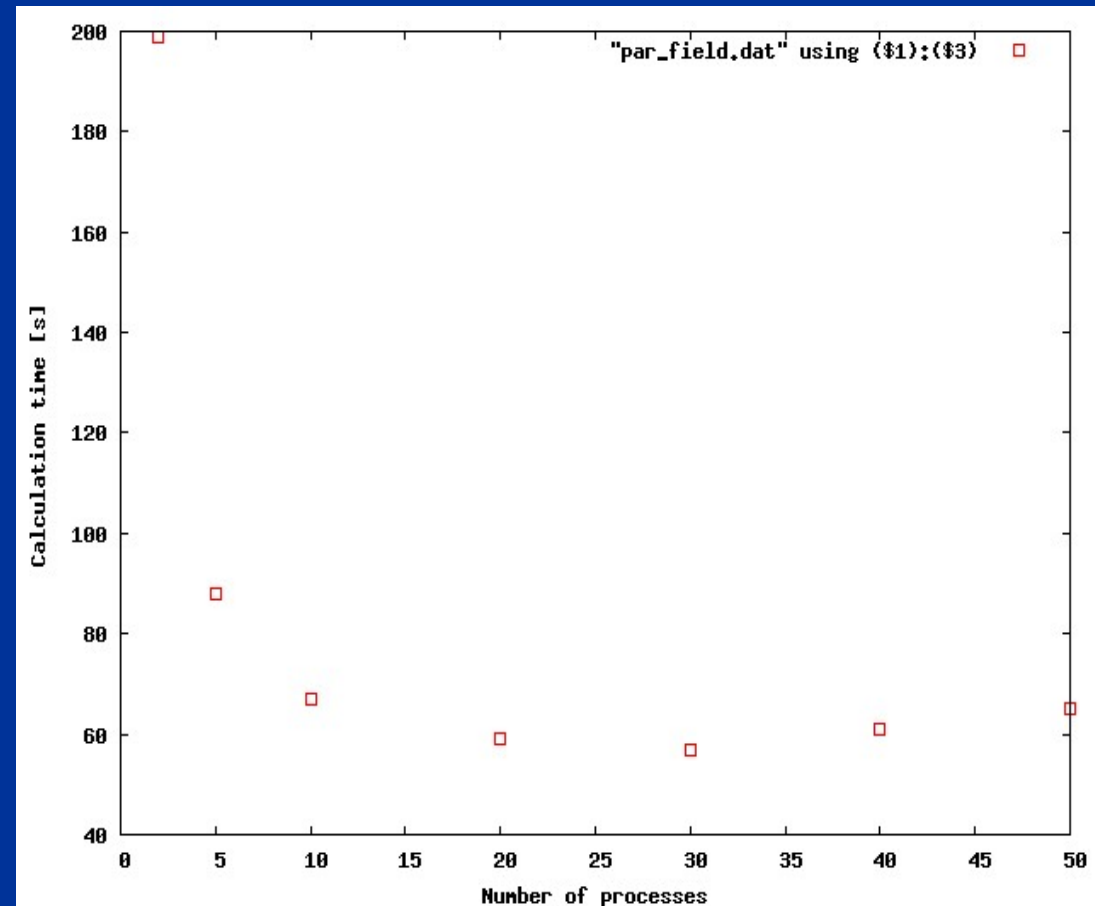
Gabor lens - Field

- Mesh $61 \times 61 \times 217 = 807457$ points
- Number of processors
 - 2 – 50
- 150 iteration steps \Rightarrow residual norm $\sim 10^{-10} =$ accuracy
- Computation time
 - 60 – 200 s



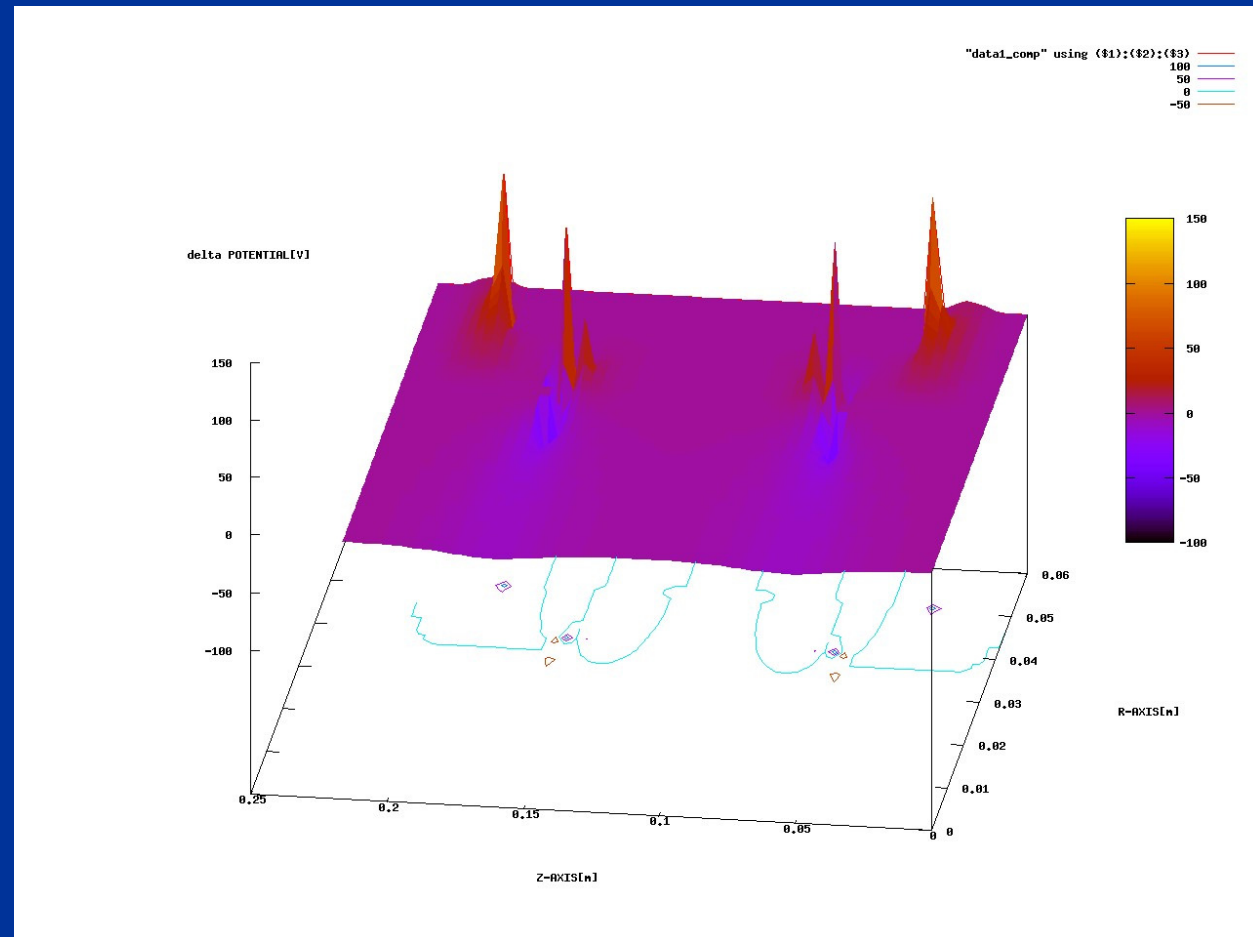
Gabor lens - Field

- Time scaling
- Comparison with 2D-Program – 0.01%
- By changing of mesh-resolution also on axis variation in 0.01%



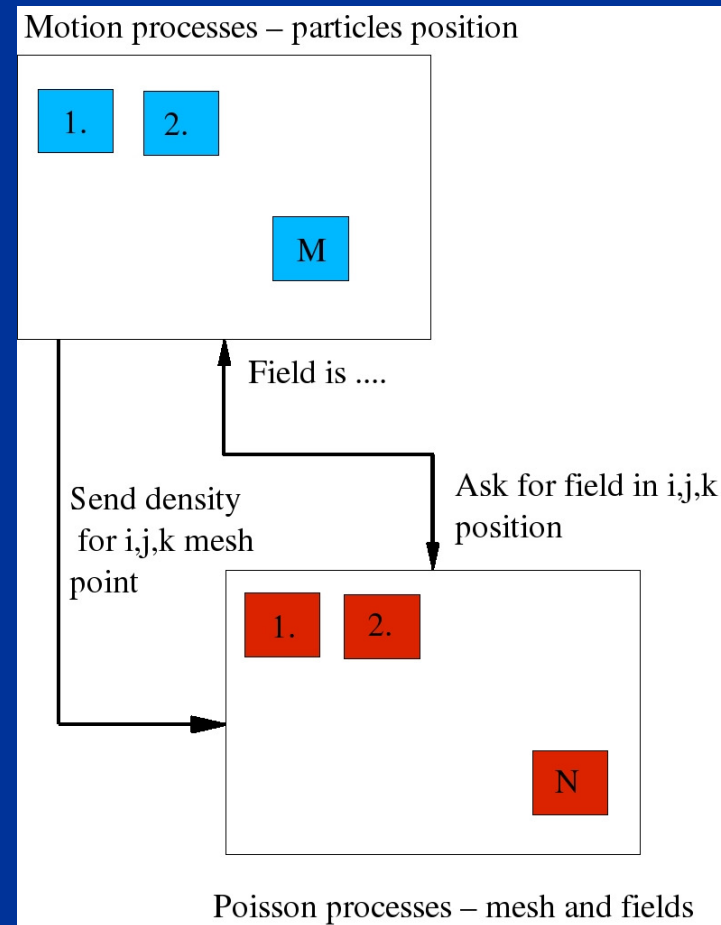
Gabor lens - Field

Comparison
between 2
simulations –
 $\text{step1} = 2 * \text{step2}$



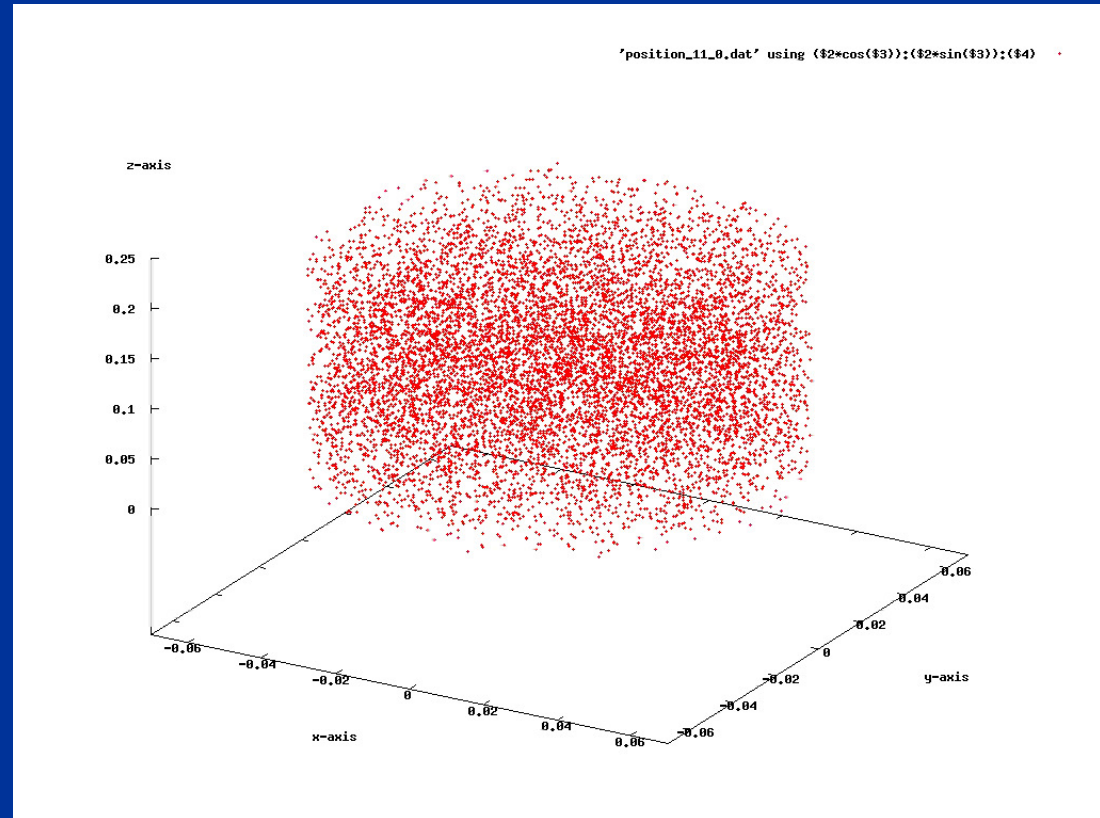
Gabor lens - Motion

- PIC - Method
- Boundary condition – electrodes
- Poisson processes \Leftrightarrow Motion processes – sending and receiving of data
- 1st test only with external field \Rightarrow no space charge effects

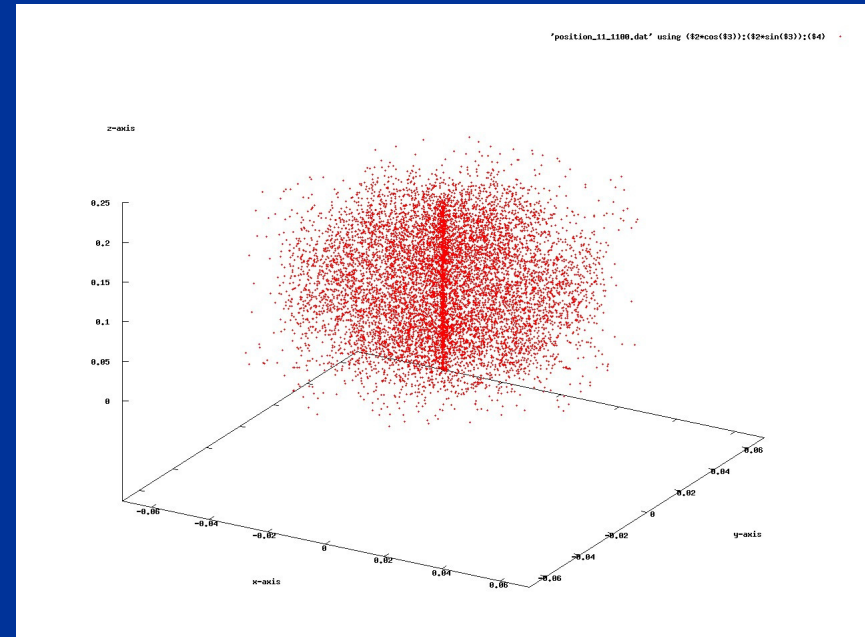
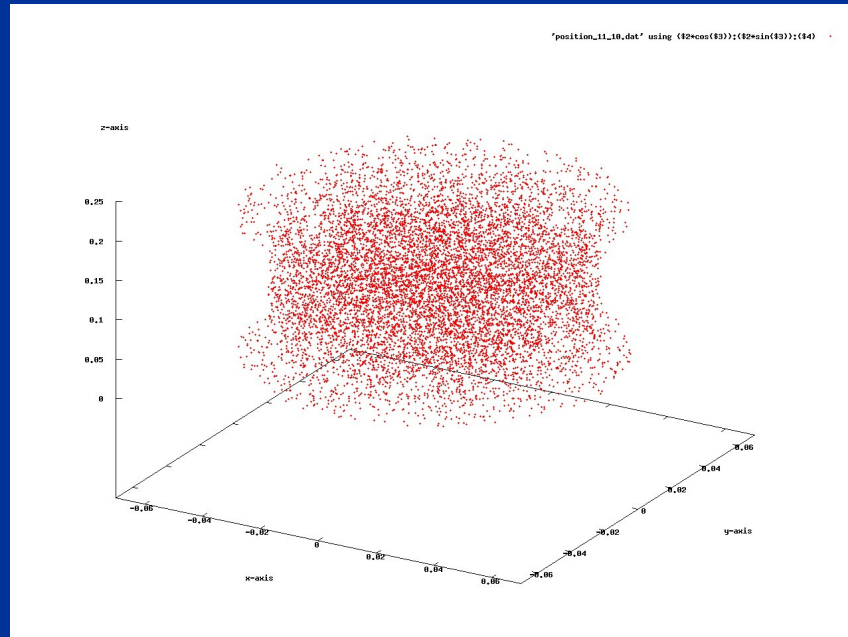


Gabor lens - Motion

- First results
 - $B=0.007T$
 - $U=2kV$
 - Initial kinetic energy $\langle 0 - 4keV \rangle$
 - Time step $dt = 4e-11s$
 - Calculation time for 2200 steps = 90min – 10000 particles per processor



Gabor lens - Motion



Conclusion and Outlook

- Magnetic surfaces were calculated – coordinate system for the accumulator
- Field calculation code was written and tested
- Motion in cylindrical coordinate was calculated

Future plans:

- PIC – Space charge effects have to be include
- Motion in accumulator – averaging through Larmor oscillation
- Long term simulation – stability !

Some calculations

$$B = 1T, n_B = \varepsilon_0 B^2 / (2m_p) = 2.65 \cdot 10^{15} m^{-3}$$

$$\delta B / B \approx (n_e / n_B)^2 \left(\frac{a}{c / \omega_c} \right)^2$$

$$\nabla^2 \phi = \frac{e}{\varepsilon_0} N(\psi) \exp\left(\frac{e\phi}{T_e(\psi)} \right)$$

$$j_{kritisch} = n_B e v = 2.65 \cdot 10^{15} \cdot 1.602 \cdot 10^{-19} \cdot 0.018 \cdot c = 2292.5 A / m^2 = 0.229 A / cm^2$$